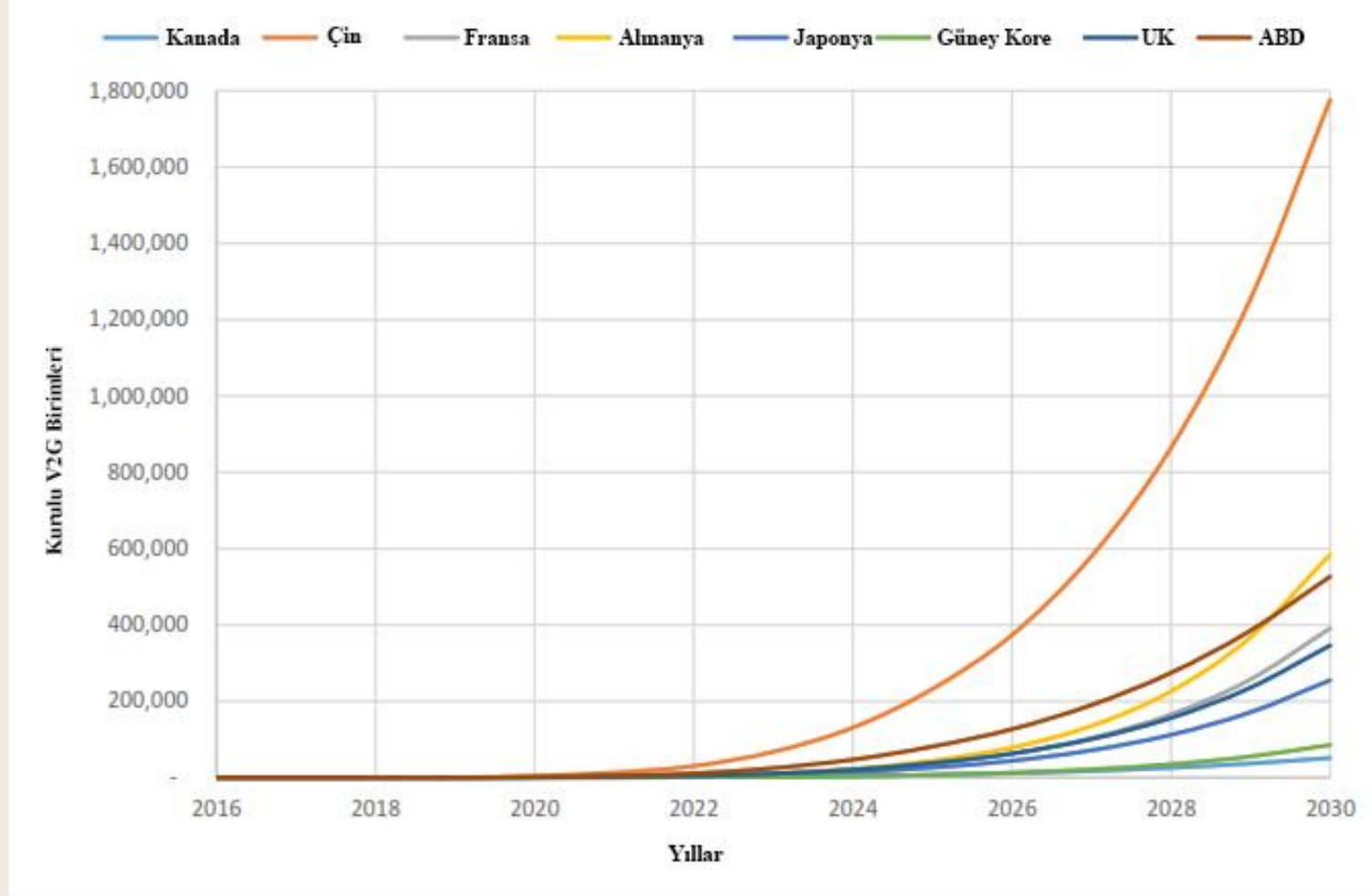
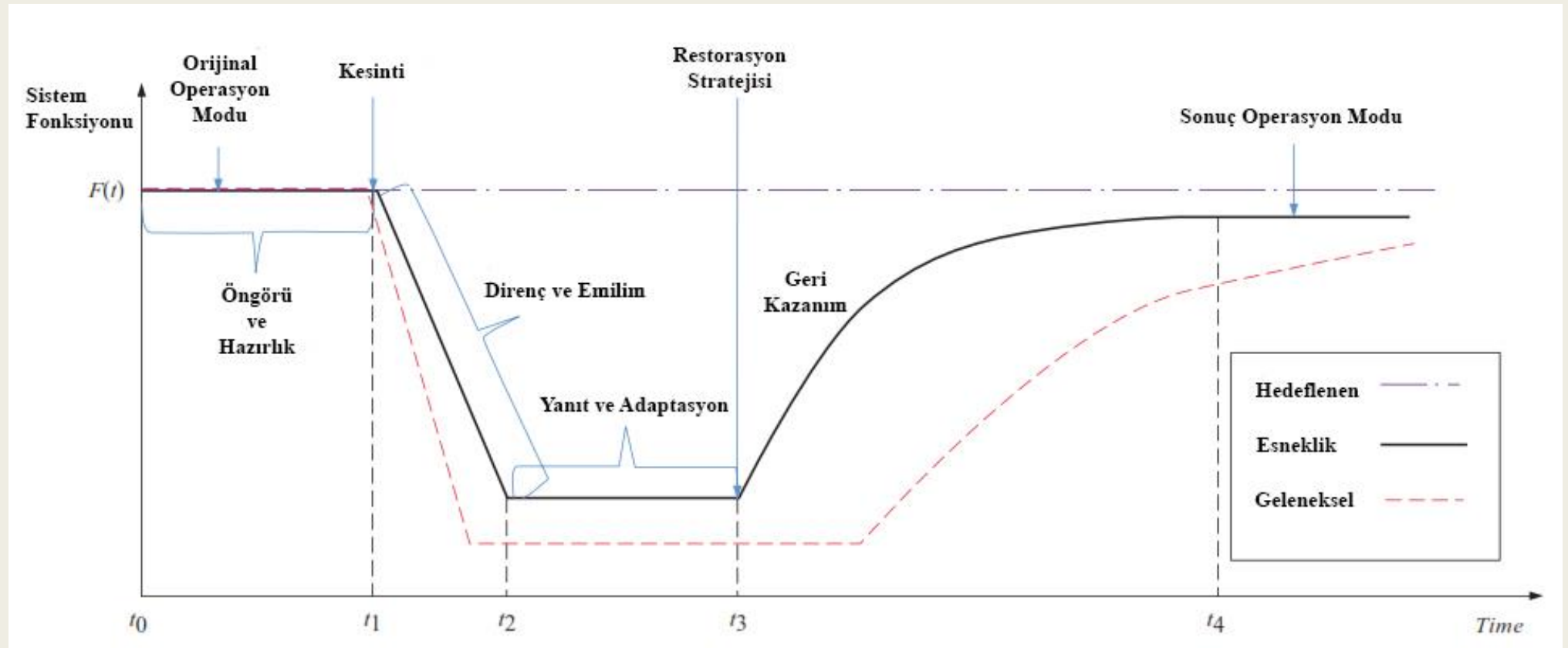


**Elektrik Güç Sisteminin Dayanıklılığını Arttırmak
İçin Elektrikli Araçların Acil Durum Kaynağı Olarak
Kullanılması Ve Optimizasyon Tabanlı Yeni Bir
Yaklaşımın Geliştirilmesi**

V2G



Dayanıklılık -Resiliency-





Bu alıřmada,

- Dağıtım sisteminin kayda değeri bir süre boyunca kullanılamaması durumunda elektrik arz-talep güvenliğinin sağlanması için elektrikli araç filosunun deřarj gücü kapasitesi kullanılarak yeterli bir enerji kaynağı oluřturulması dođrultusunda bir optimizasyon modeli oluřturulmuřtur.

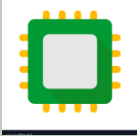




Literatürden elde edilen verilere dayanarak tüketim için kritik ve kritik olmayan yük profilleri oluşturulup buna göre talebin karşılanması amaçlanmıştır.



Gerçekçi bir yaklaşım geliştirmek amacıyla, TLC'nin New York taksileri için kaydedilmiş yolculuk kayıtları ile regresyon yapılarak lokasyonlara göre olası taksi sayısı tahmin edilip, buna göre optimizasyon modeli geliştirilmiştir.

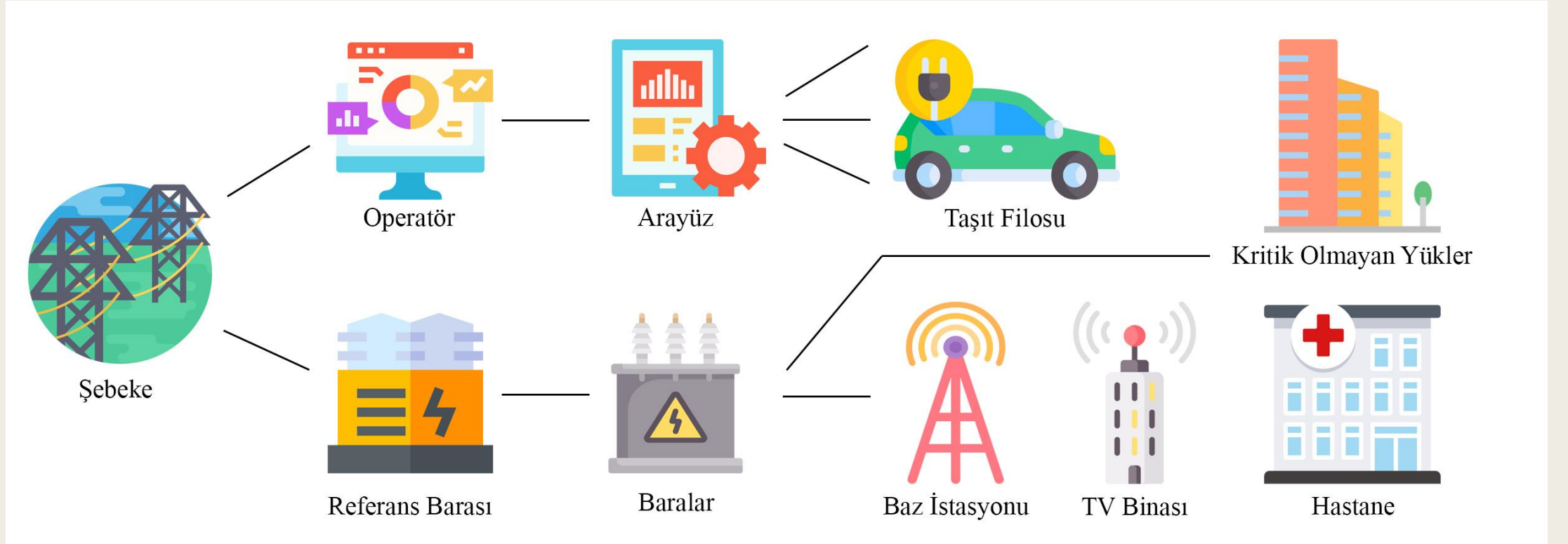


Bu optimizasyon modelinin programlanmasında karmaşık tam sayılı lineer programlama yöntemi (Mixed Integer Linear Programming – MILP) kullanılmış olup modelin benzetim çalışması Python 2.7 versiyonunun PuLP 1.6.8 açık kaynak kodlu kütüphanesi içinde CPLEX ticari optimizasyon çözücüsü ile yapılmıştır.



Her EV güç kaynağı olarak kabul ederek, bunların tedarik, deşarj süresi, kullanım limiti gibi parametreleri hesaplanmıştır.

Sistemin Tanıtımı



Zaman Serisi Tahmin Yöntemleri

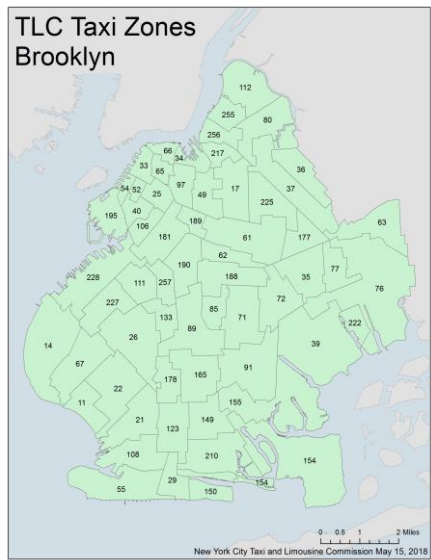
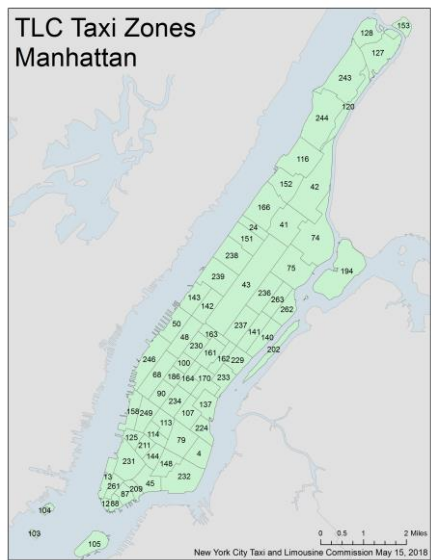
- SARIMA - ARIMA
- Holt-Winters
- Linear Regression
- PROPHET

Regresyon analizi

- İki ya da daha çok değişken arasındaki ilişkiyi matematiksel bir denklem yardımıyla ifade eden bir analiz metodudur.

PROPHET

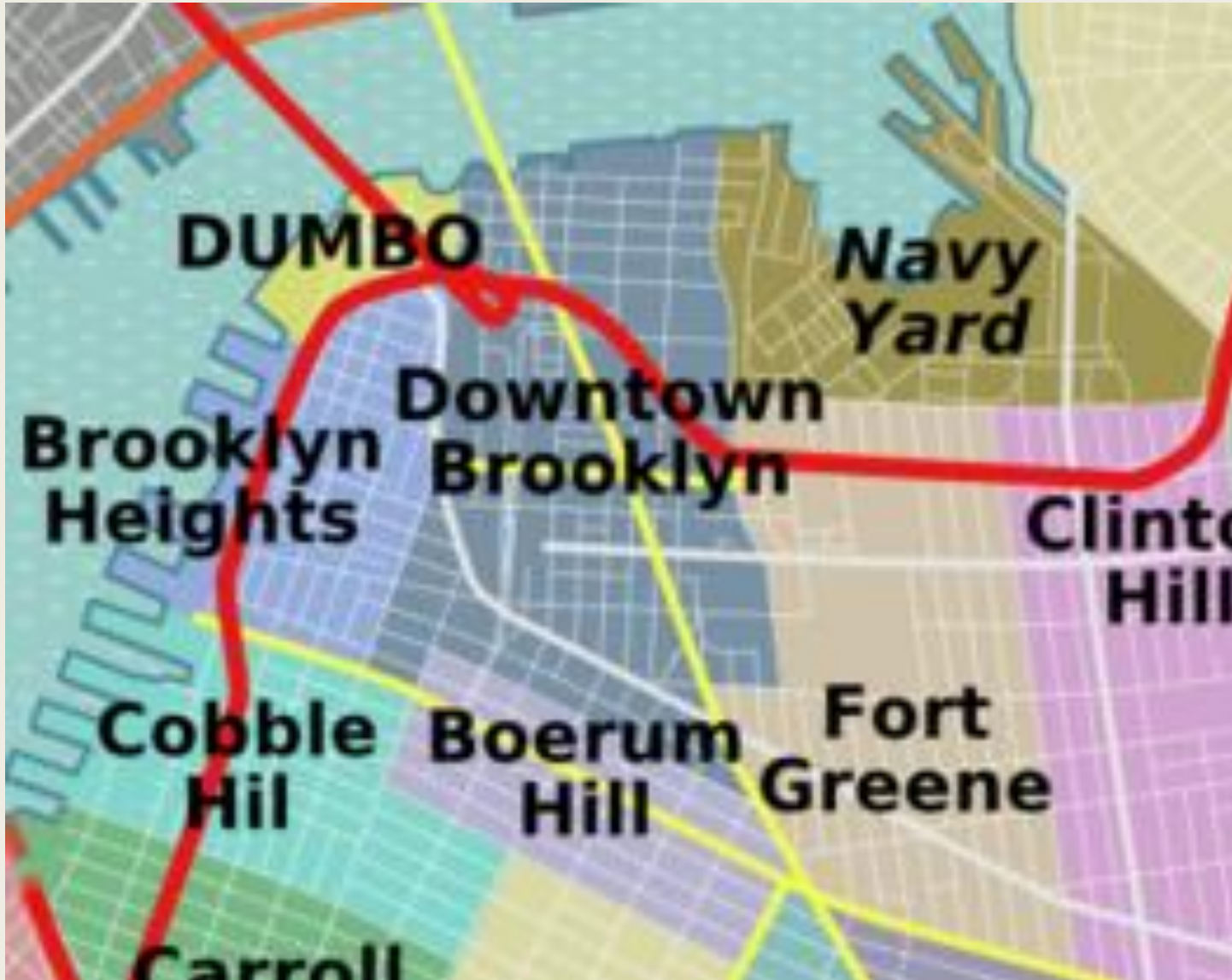
- Facebook tarafından 2017'de scikit-learn kütüphanesi üzerine inşa edilen ve mevsimsel etkiler üzerinden tahmin etmek için kullanılan bir prosedürdür.



TLC Trip Record Data

- Sarı taksi yolculuk kayıtları

```
VendorID,tpep_pickup_datetime,tpep_dropoff_datetime,passenger_count,trip_distance,RatecodeID,store_and_fwd_flag,PULocationID,DOLocationID,payment_type,fare_amount,extra_charges,tip_amount,tolls_amount,improvement_surcharge,total_amount
1,2019-01-01 00:46:40,2019-01-01 00:53:20,1,1.50,1,N,151,239,1,7,0.5,0.5,1.65,0,0.3,9.95,
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2,2019-01-01 00:52:37,2019-01-01 01:03:42,1,2.10,1,N,151,142,2,9,5,0.5,0.5,0,0,0.3,10.8,
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```

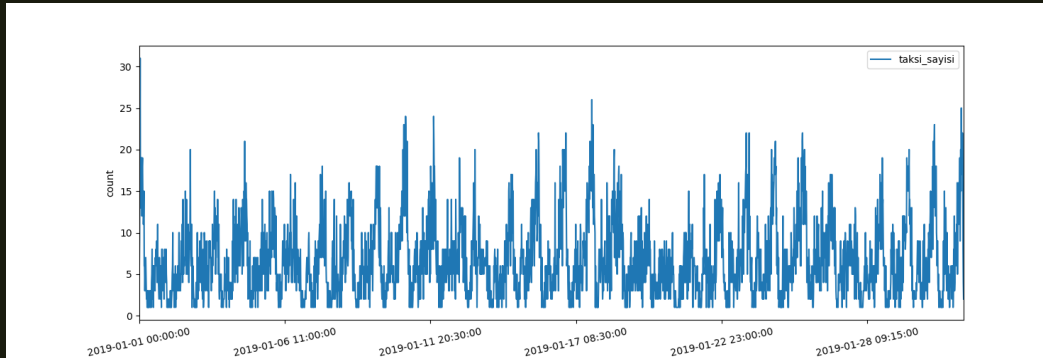
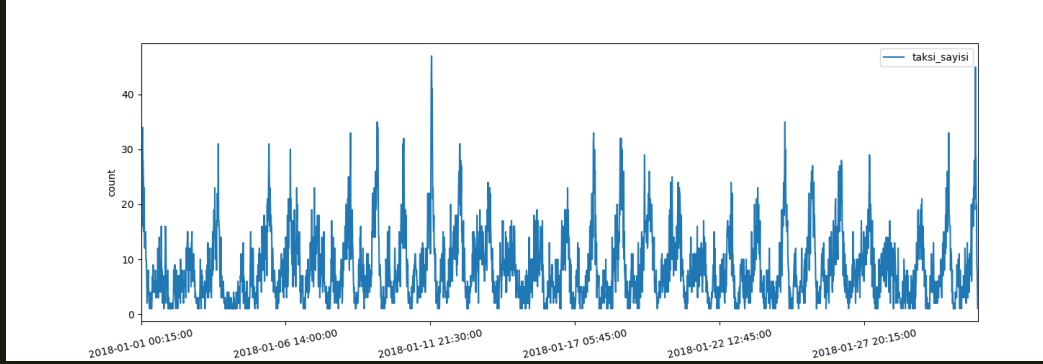
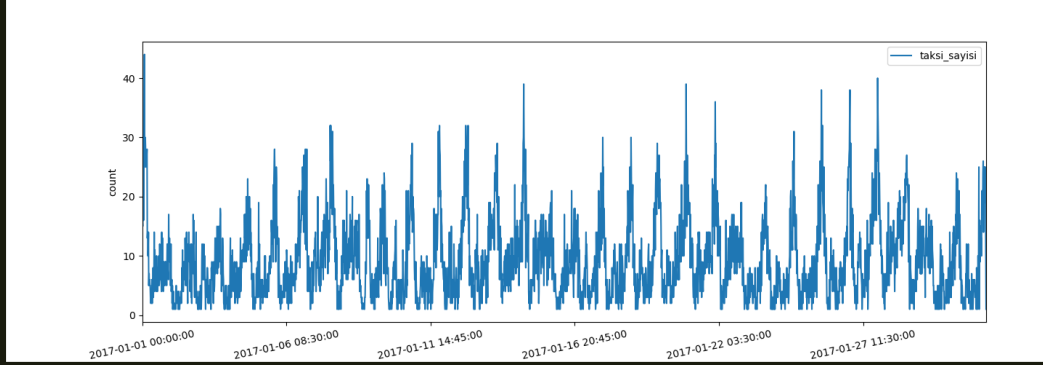


BROOKLYN MAP

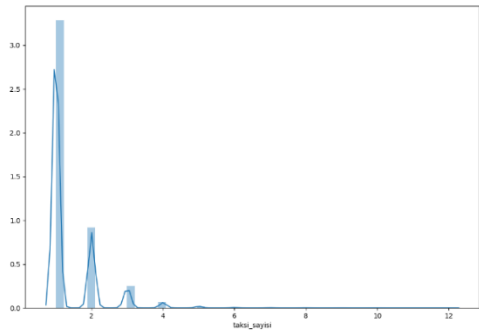
- Downtown Brooklyn

Neighborhoods:

- Fort Greene
- Brooklyn Navy Yard
- Brooklyn Heights
- Boerum Hill



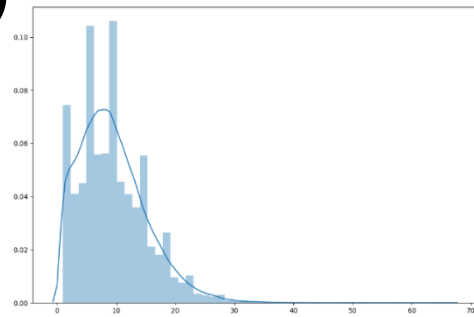
- Downtown Brooklyn
2017-2018-2019
Yıllarına Göre Taksi
Sayısı



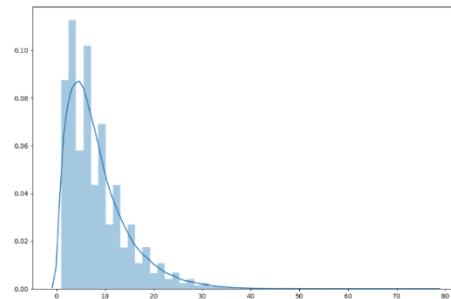
1. Brown Brooklyn
 2. Hill
 3. Heights
 4. Navy Yard

5. Fort Greene

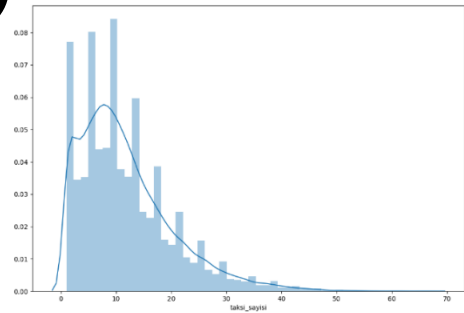
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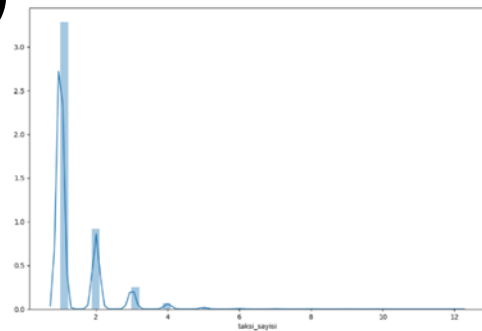
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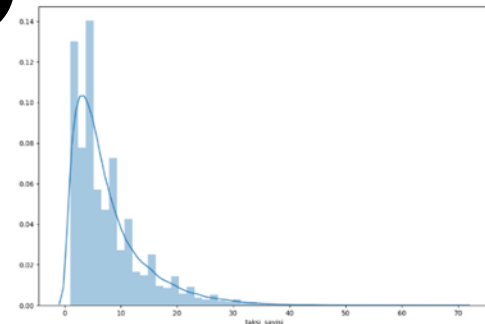
3



4



5



Polynomial Regression

(yıl, ay, gün, dilim, haftanın günü, saat)

■ 2019-01-07 10:12:00 • [12]

■ 2019-01-08 10:12:00 • [15]

■ 2019-01-11 10:12:00 • [9]

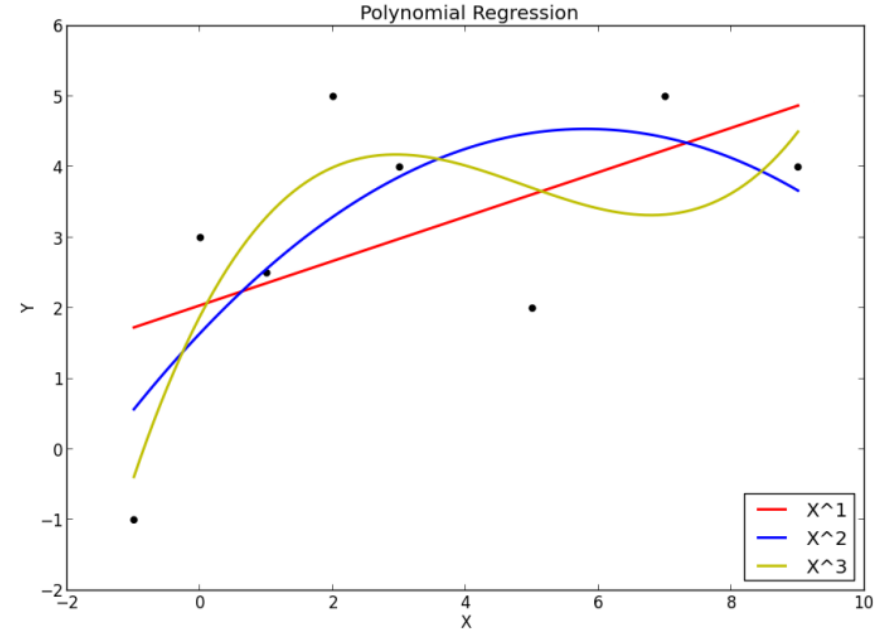
[[10.42104167]]

■ 2019-01-15 10:12:00 • [19]

■ 2019-01-16 10:12:00 • [20]

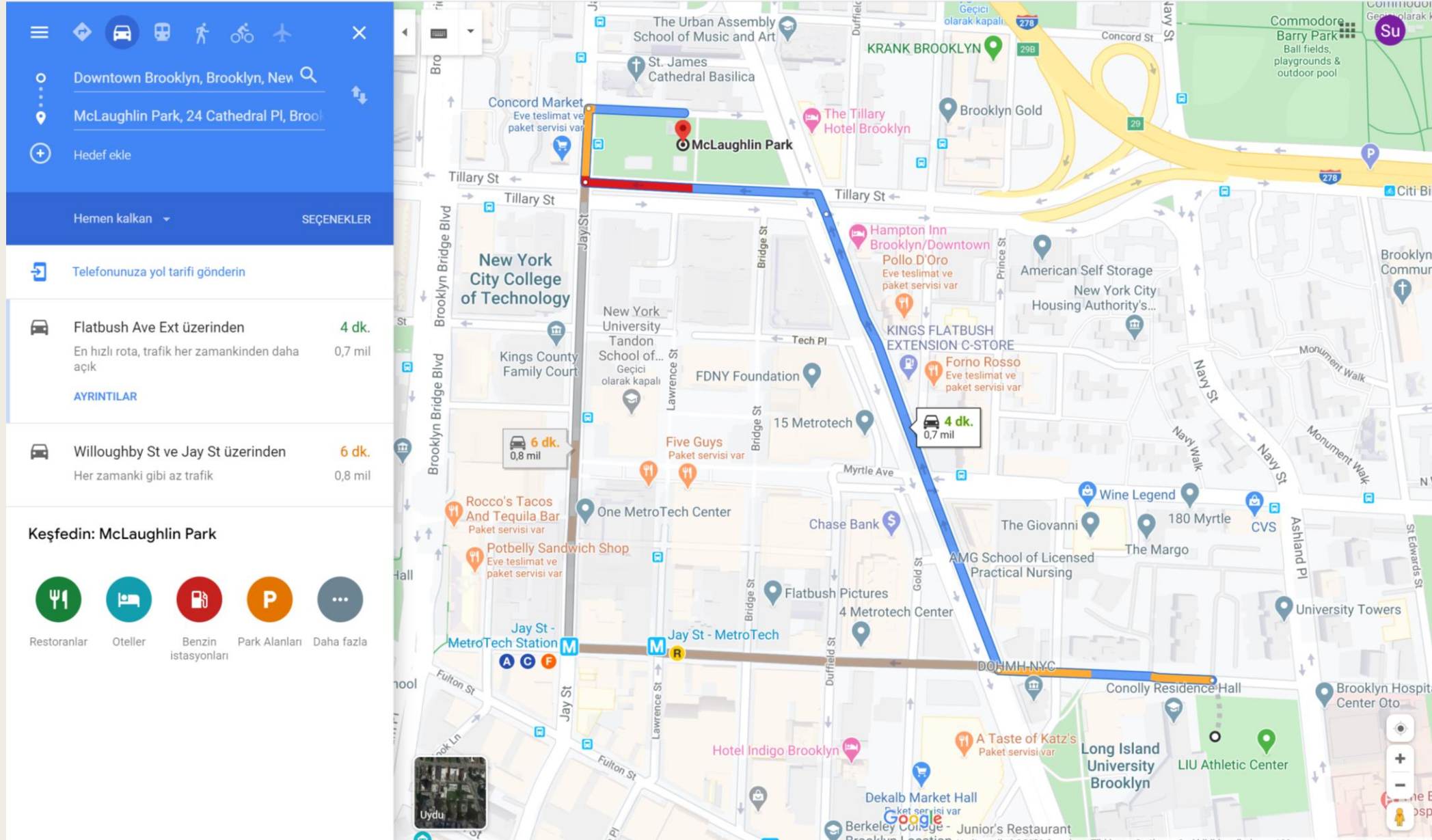
■ 2019-01-17 10:12:00 • [7]

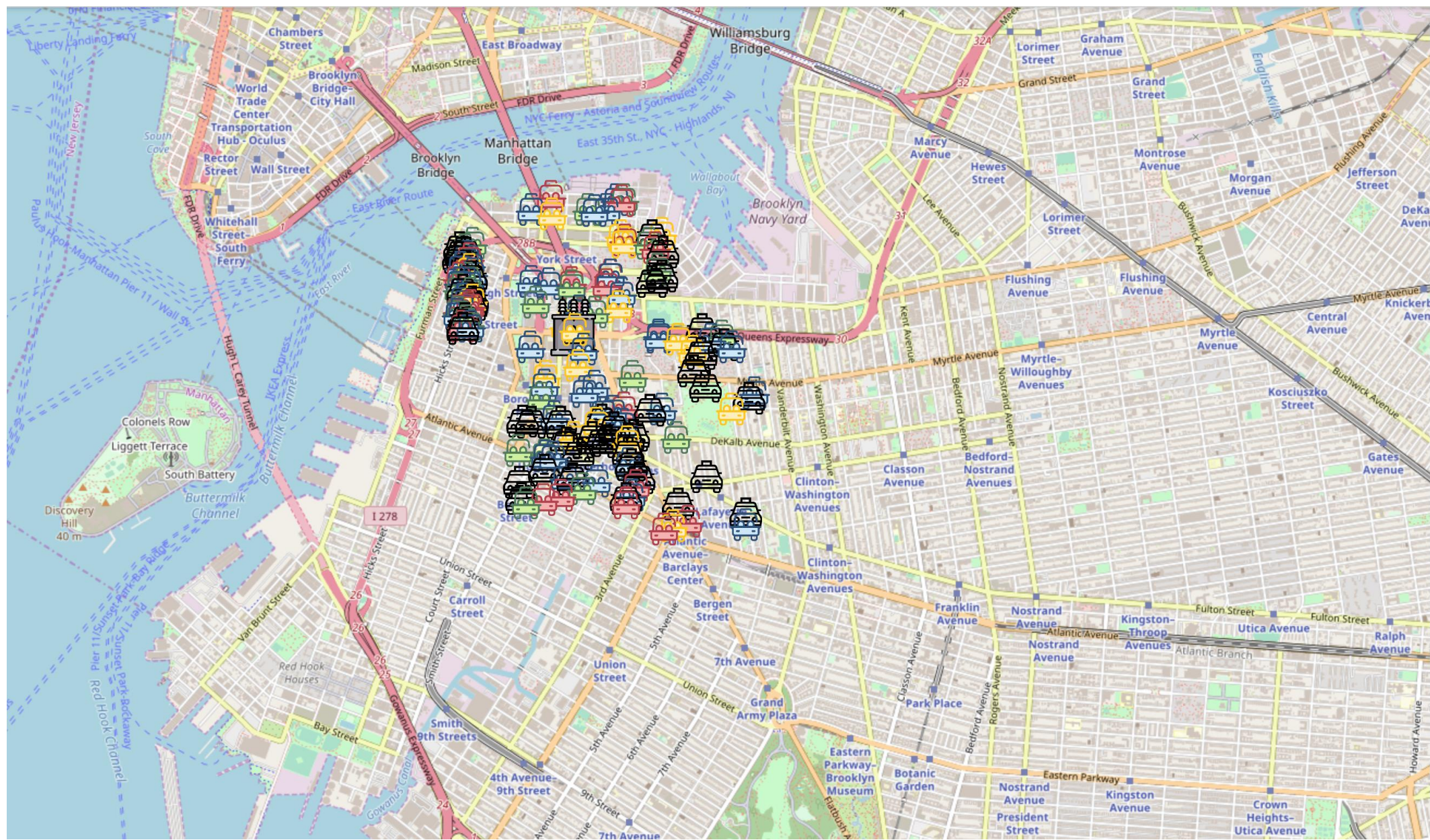
■ 2019-01-22 10:12:00 • [11]



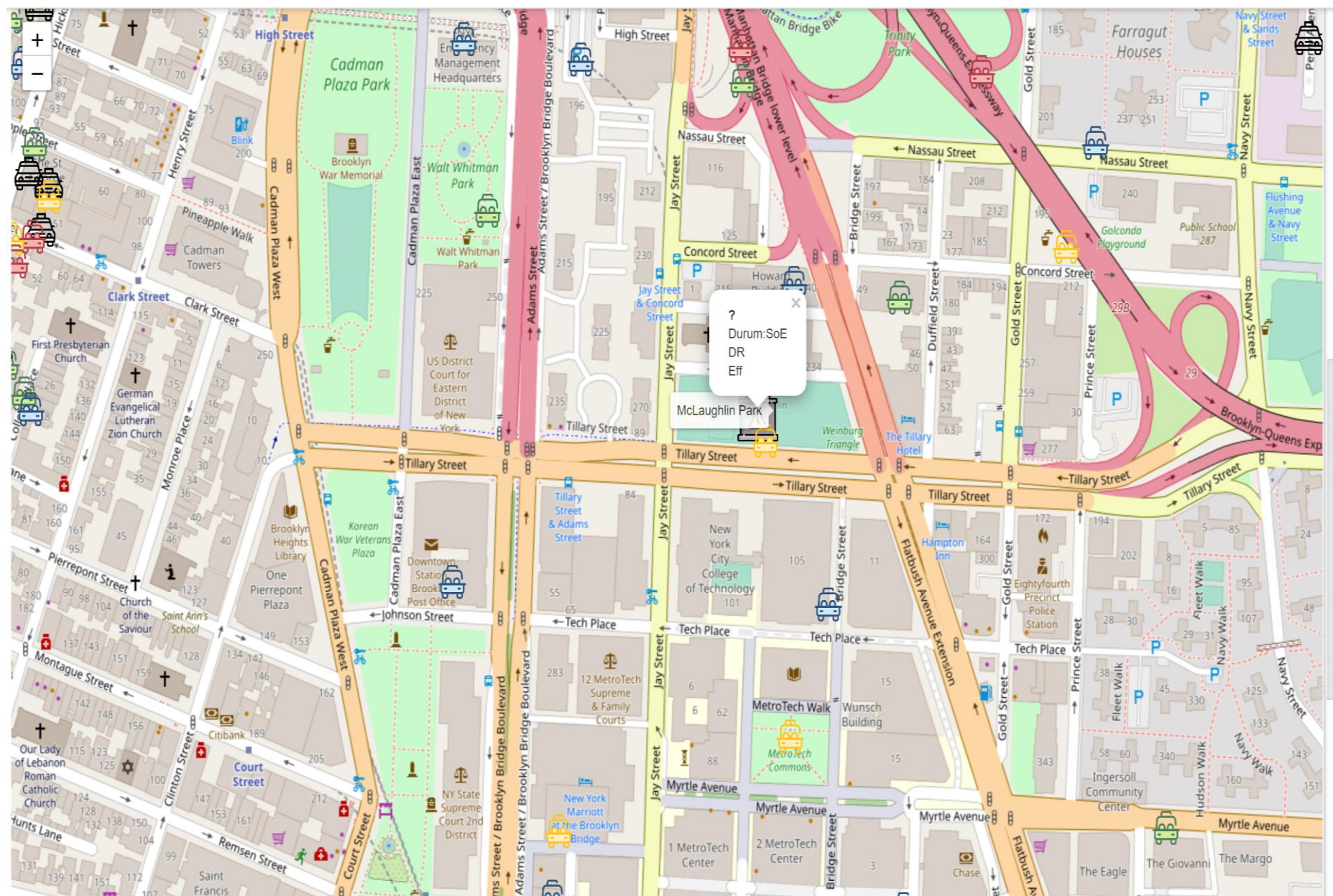
EV_ID	Distance
EV1	
EV2	0.8 mil
EV3	0.6 mil
EV4	0.3 mil
EV5	0.2 mil
EV6	
EV7	0.8 mil
EV8	
EV9	
EV10	0.3 mil

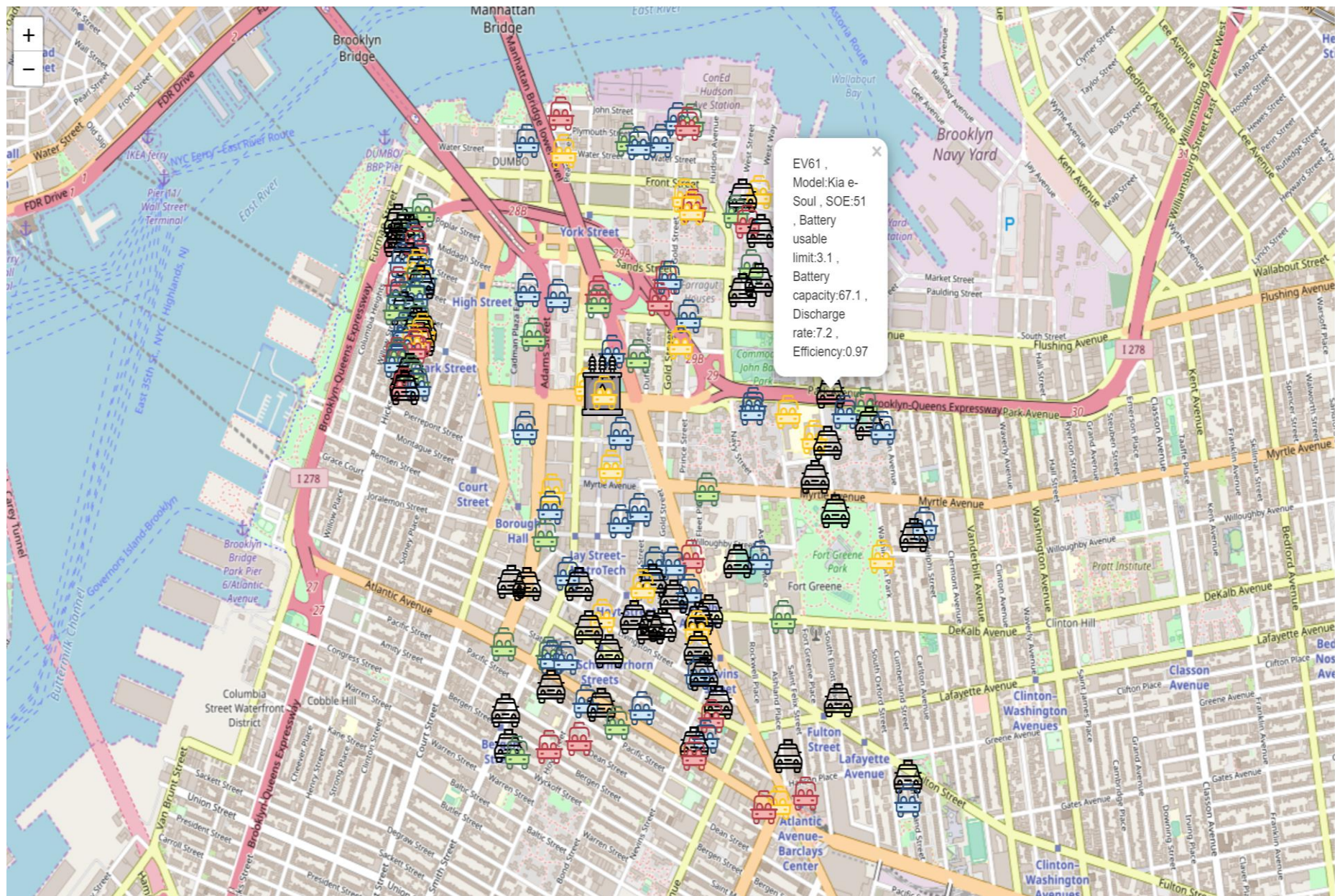
lat	long
40.69148	-73.98
40.69796	-73.9891
40.70426	-73.9879
40.69631	-73.986
40.69529	-73.9895
40.69642	-73.9948
40.70109	-73.9947
40.69082	-73.9871
40.69815	-73.994



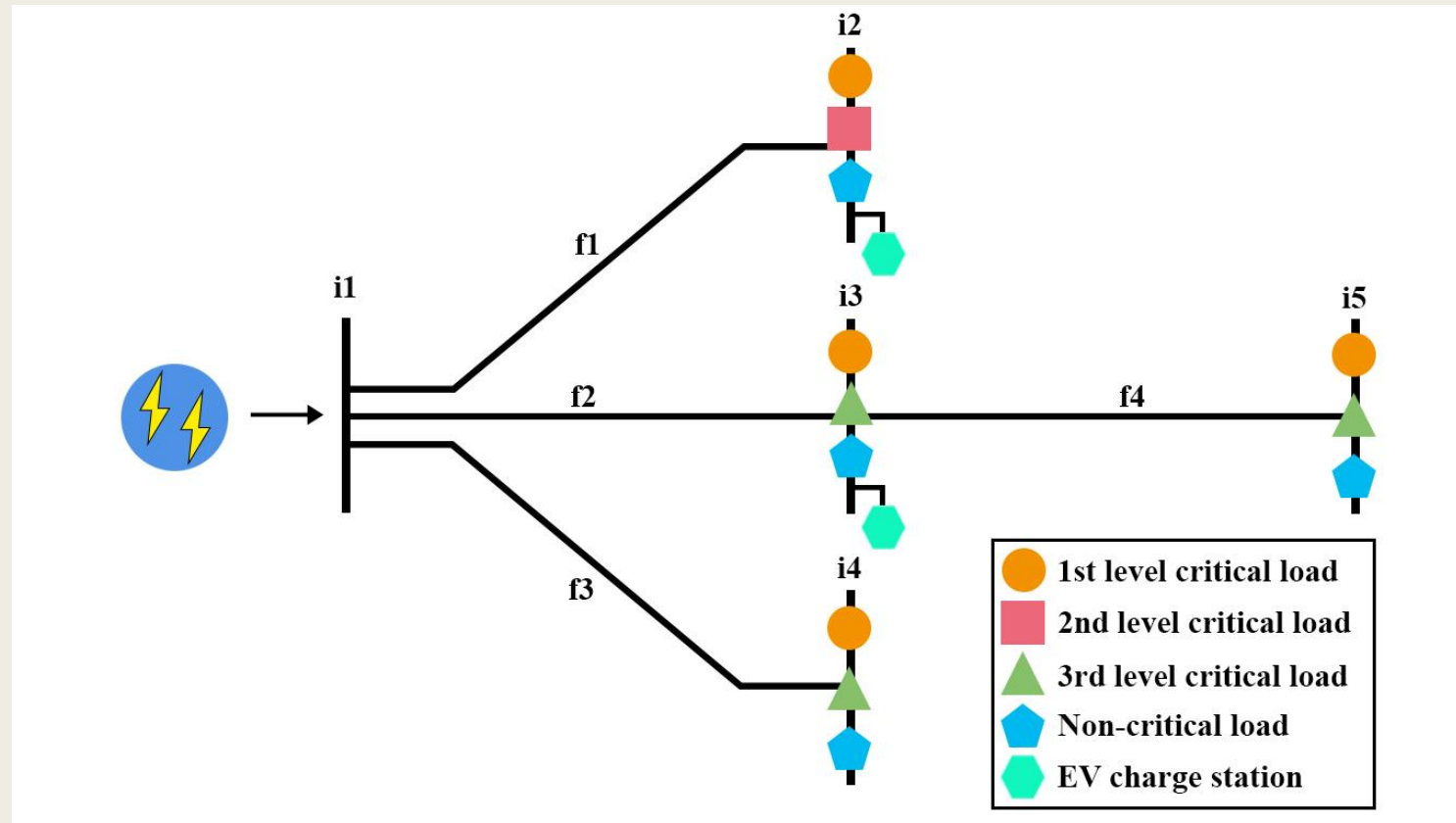




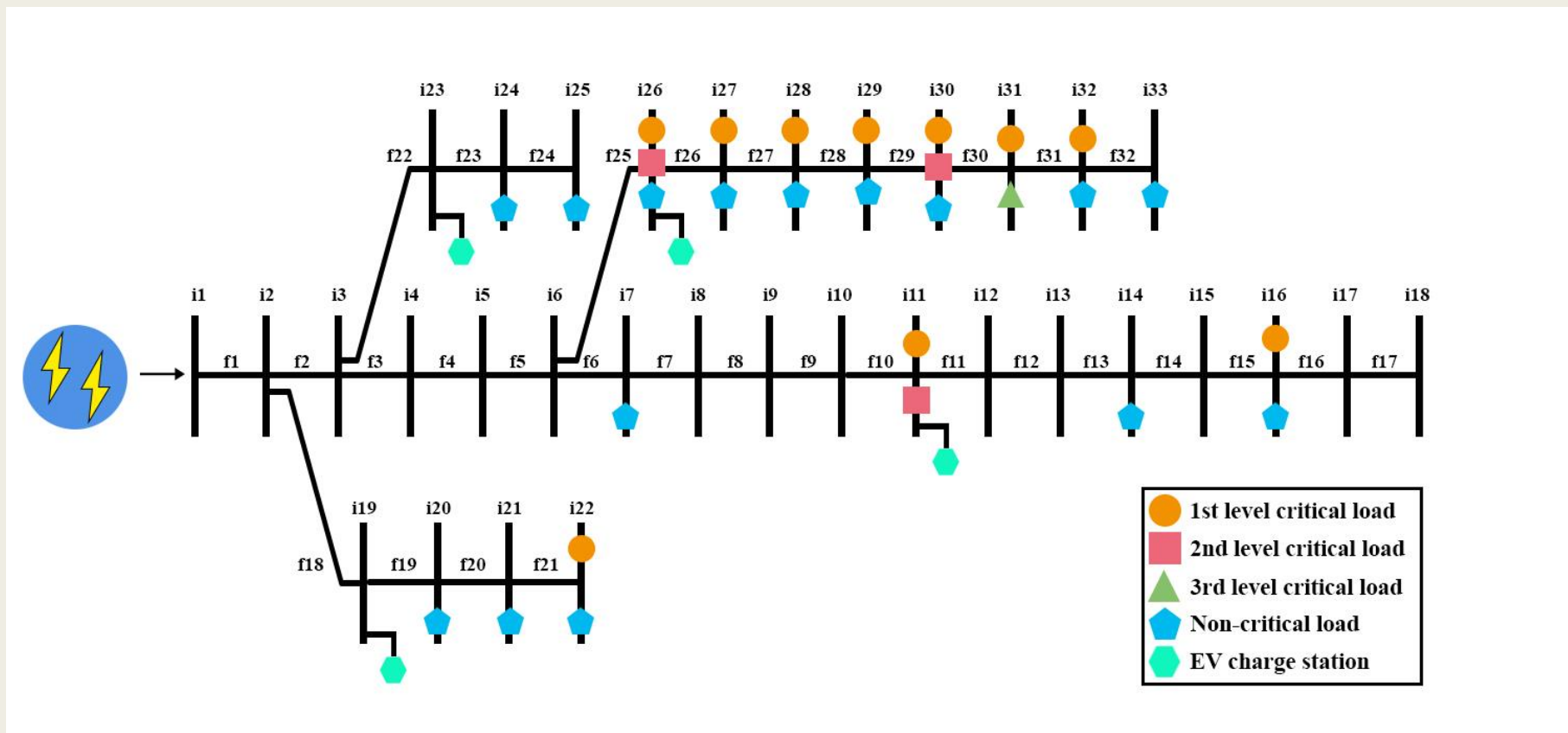




5 Baralı Sistem



IEEE-33 Baralı Sistem



Optimizasyon Algoritması

Amaç Fonksiyonu

$$\max \sum_i \sum_t \sum_d (w_d \cdot u_{i,t}^d) - \sum_t \lambda_t + \sum_i \sum_e \sum_t \beta_{i,e,t}$$

EV Bağlantı Denklemleri

$$\alpha_{i,e,t} = 0 \quad , \quad i \in i', \forall e, t < t_{event}, t \geq t_{dep}$$

$$\alpha_{i,e,t} = 0 \quad , \quad i \notin i', \forall e, \forall t$$

$$\sum_e \alpha_{i,e,t} < \kappa_i \quad , \quad i \in i', t = t_{event}$$

$$\alpha_{i,e,t} \leq b_{i,e} \quad , \quad i \in i', \forall e, t = t_{event}$$

$$\beta_{i,e,t} = 1 - \alpha_{i,e,t} \quad , \quad \forall i, \forall e, \forall t$$

EV Deşarj Denklemleri

$$\begin{aligned} P_{i,e,t}^{dis} &\geq 0 \quad , \quad \forall i, \forall e, \forall t \\ P_{i,e,t}^{dis} &\leq \alpha_{i,e,t} \cdot DR_e \quad , \quad i \in i', \forall e, \quad t_{event} + 1 \leq t < t_{dep} \end{aligned}$$

$$SOE_{i,e,t} = 0 \quad , \quad \forall i, \forall e, t < t_{event}, t \geq t_{dep}$$

$$SOE_{i,e,t} = soe_{e,t} \cdot \alpha_{i,e,t} \quad , \quad \forall i, \forall e, t = t_{event}$$

$$SOE_{i,e,t} = (soe_{e,t-1} - soe_e^{loss}) \cdot \alpha_{i,e,t} \quad , \quad \forall i, \forall e, \quad t = t_{event} + 1$$

$$SOE_{i,e,t} = SOE_{i,e,t-1} - \left(\frac{P_{i,e,t-1}^{dis}}{\eta_e} \right) \cdot \Delta T \quad , \forall i, \forall e, t_{event} + 1 \leq t < t_{dep}$$

$$SOE_{i,e,t} \geq SOE_{min} \cdot \alpha_{i,e,t} \quad , \quad \forall i, \forall e, t_{event} + 1 \leq t < t_{dep}$$

Güç Dengesi Denklemleri

$$P_{i,t}^{f,load} + g_i \cdot P_{i,t}^{fleet} + \sum_{\forall l \in L: i \in \Omega_l^j} f_{l,t} - \sum_{\forall l \in L: i \in \Omega_l^i} f_{l,t} = P_{i,t}^{load} \quad , \quad \forall i, \forall t$$

$$P_{i,t}^{fleet} = \sum_e P_{i,e,t}^{dis} \quad , \quad \forall i, \forall t$$

$$P_{i,t}^{load} = \sum_d u_{i,t}^d \cdot \delta_{t,d} \cdot h_{i,d} \quad , \quad \forall i, \forall t$$

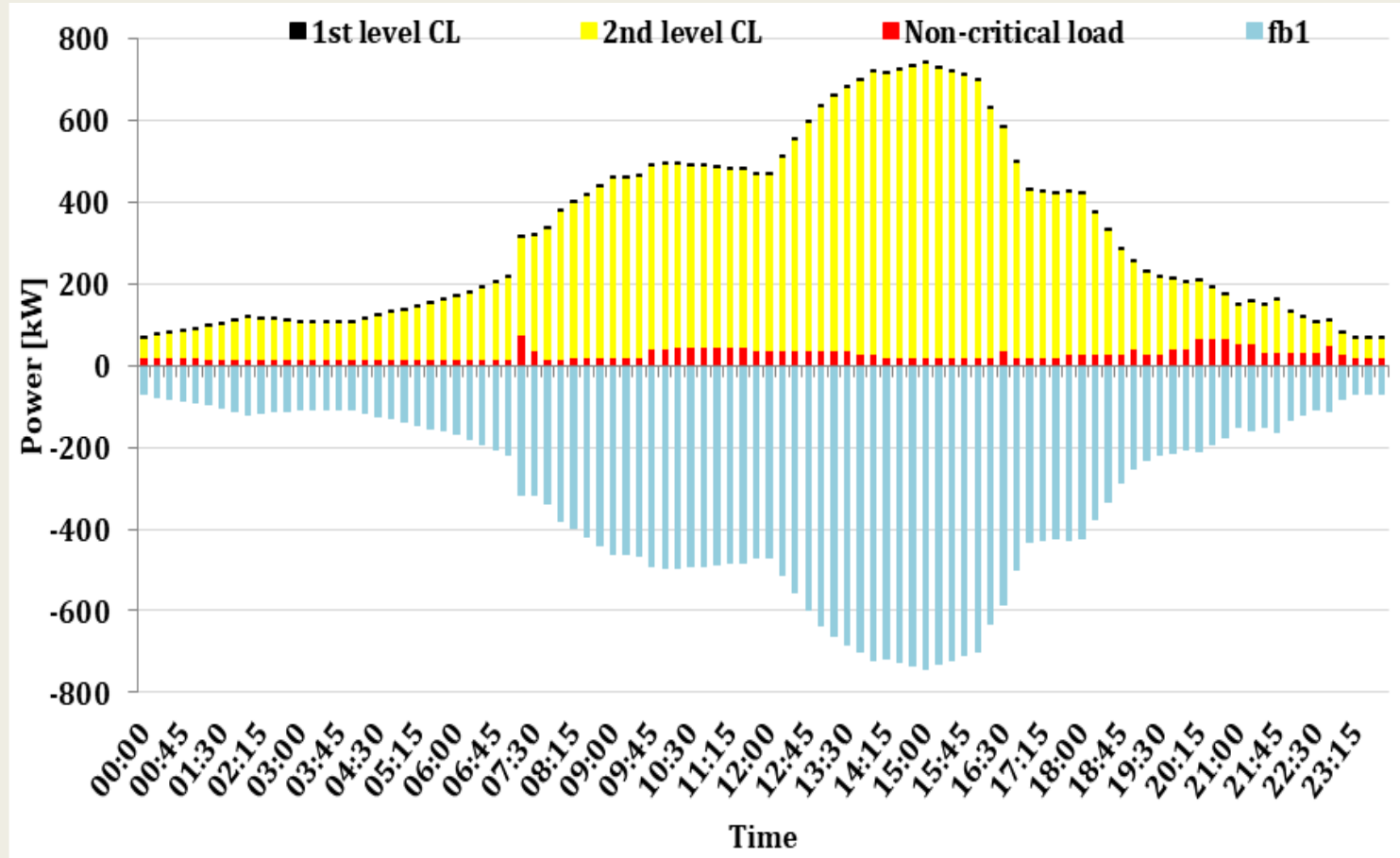
$$u_{i,t}^d \leq h_{i,d} \quad , \quad \forall i, \forall d, \forall t$$

Güç Kaybı Denklemleri

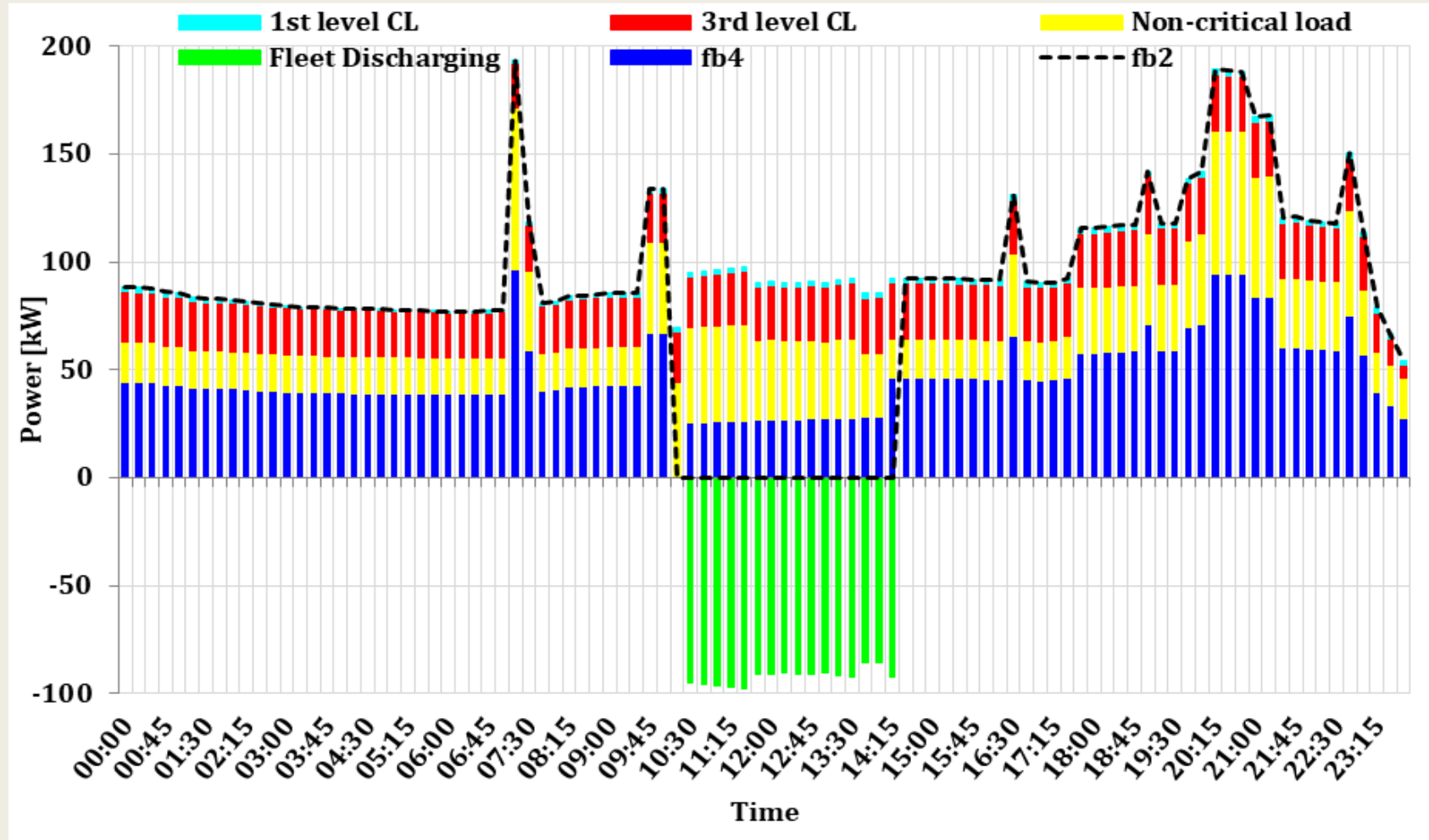
$$\begin{aligned}0 &\leq f_{l,t} \leq f_l^{max} \quad , \quad \forall l, \forall t \\ P_{l,t}^{loss} &= x \cdot f_{l,t} + y \cdot f_{l,t}^2 \quad , \quad \forall l, \forall t \\ P_{l,t}^{loss} &= x \cdot f_{l,t} + y \cdot F_{l,t} \quad , \quad \forall l, \forall t \\ \sum_p z_{l,t,p} &= 1 \quad , \quad \forall l, \forall t \\ f_{l,t} &= \sum_p X_p \cdot z_{l,t,p} \quad , \quad \forall l, \forall t \\ F_{l,t} &= \sum_p Y_p \cdot z_{l,t,p} \quad , \quad \forall l, \forall t\end{aligned}$$

$$\begin{aligned}P_{i,t}^f &= P_{i,t}^{f,load} + \lambda_t \quad , \quad i = 1, \forall t \\ 0 &\leq P_{i,t}^f \leq P_i^{f,max} \quad , \quad i = 1, \forall t \\ \lambda_t &= \sum_{l \in L} P_{l,t}^{loss} \quad , \quad \forall t \\ P_{i,t}^{f,load} &= 0 \quad , \quad i \neq 1, \forall t \\ P_{i,t}^f &= 0 \quad , \quad i \neq 1, \forall t\end{aligned}$$

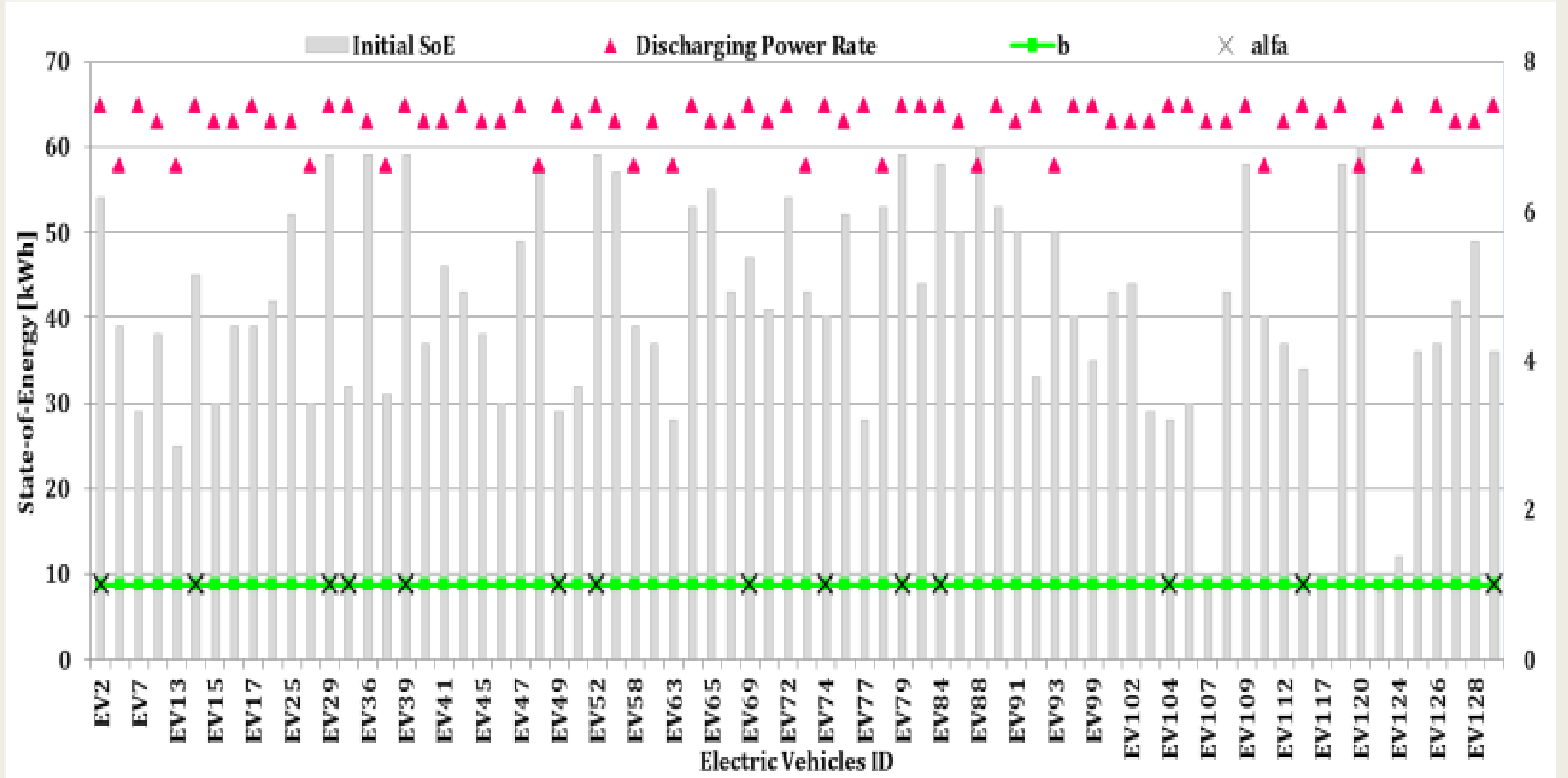
SONUÇLAR



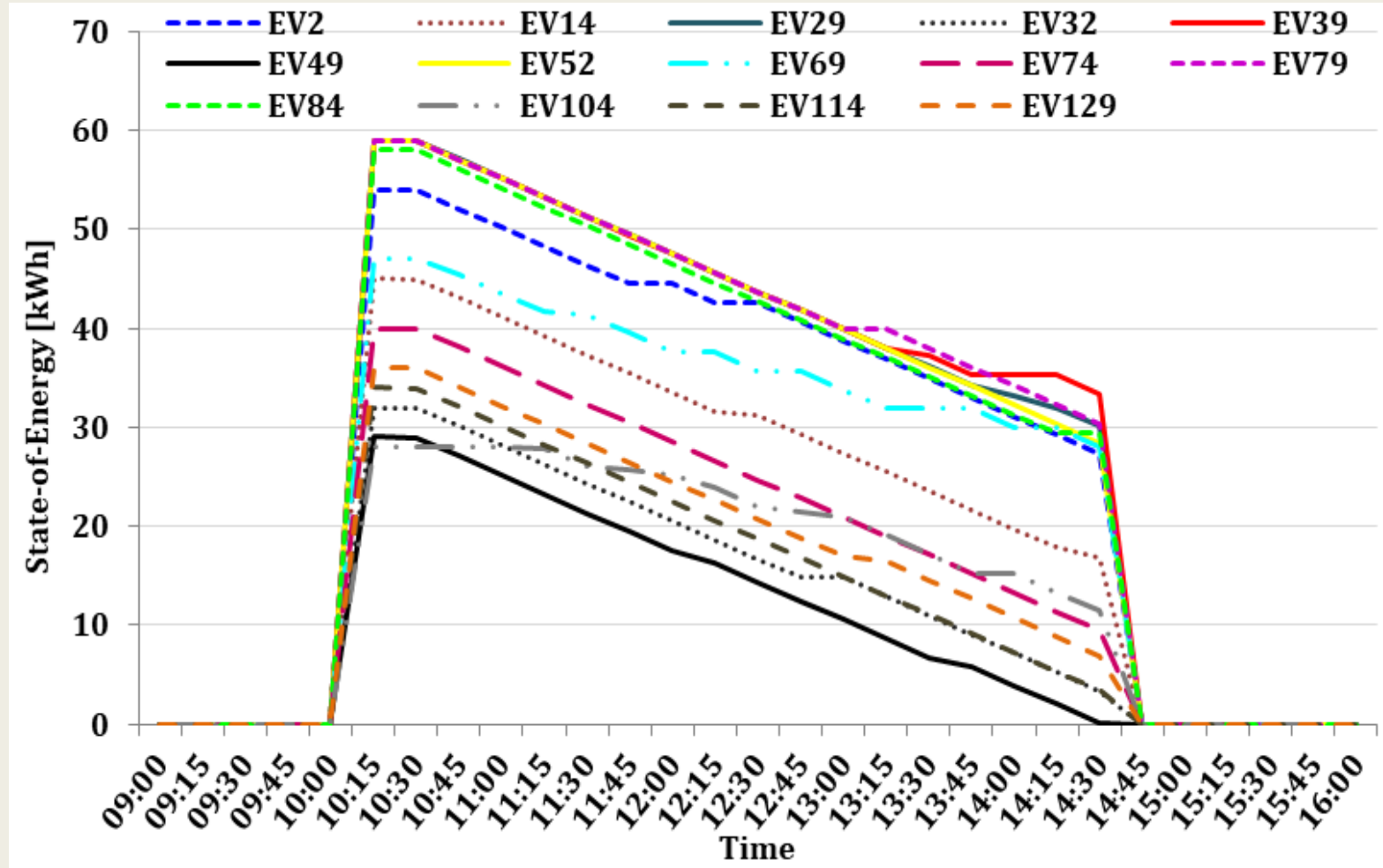
5 Baralı Sistemde i2 Barasının Simülasyon Süresince Güç Dengesi



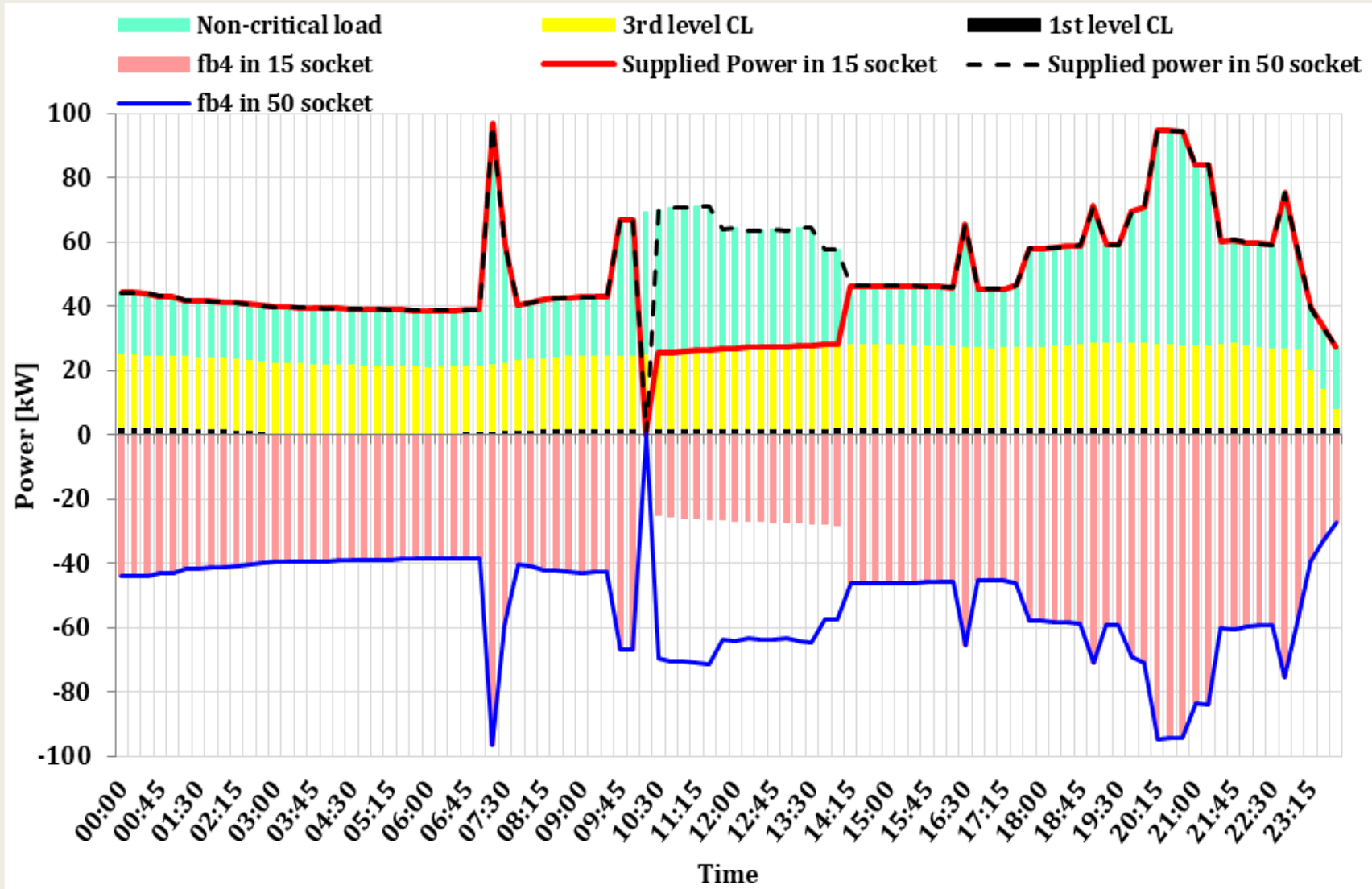
5 Baralı Sistemde i3 Barasının Simülasyon Süresince Güç Dengesi



5 Baralı Sistemde i3 Barası İçin EV Arızaya Yönlendirme Karar Verileri

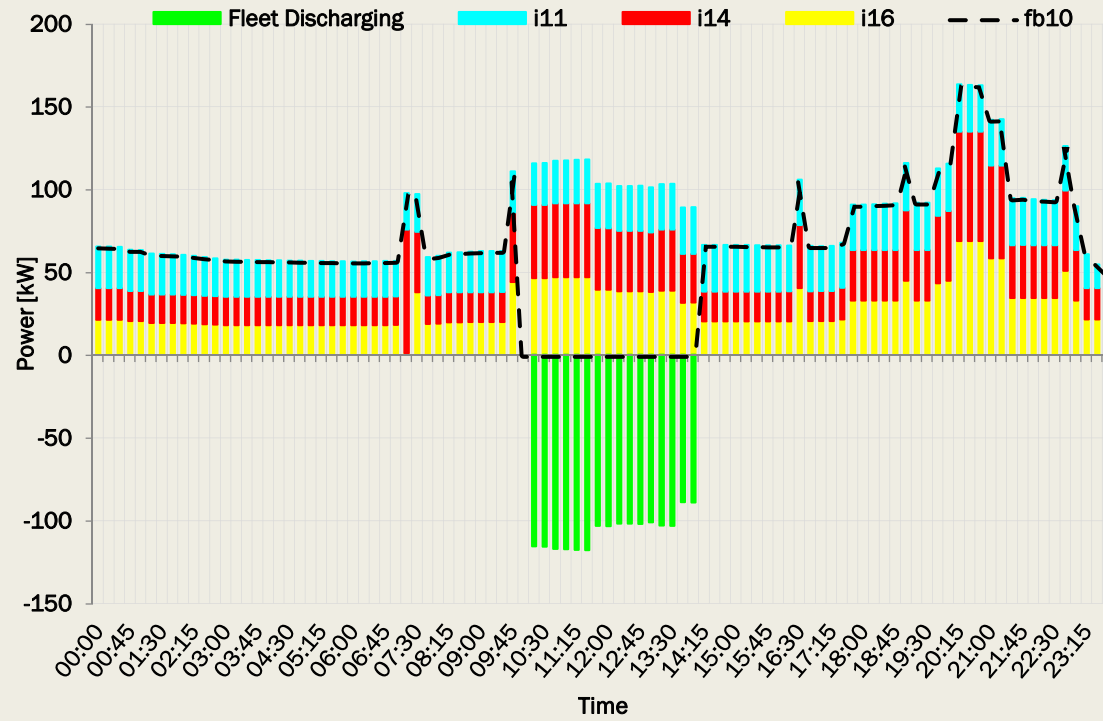


5 Baralı Sistemde i3 Barası İçin Etkinliğe Katılan Taşıtların SOE Durumları

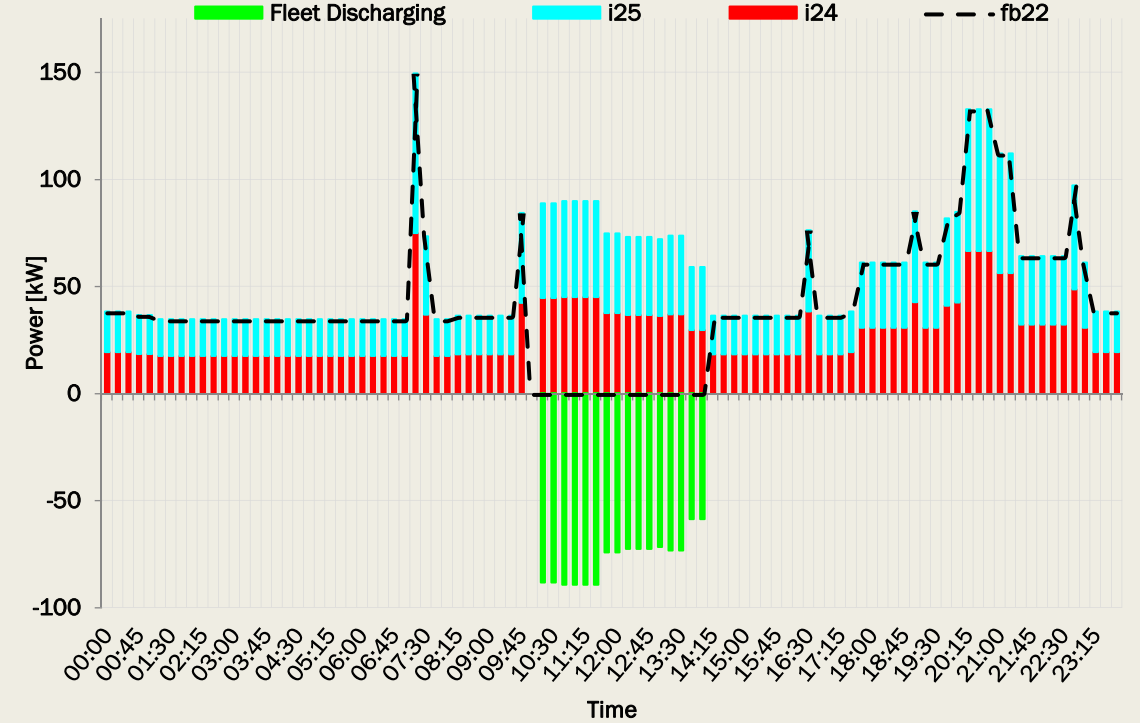


5 Baralı Sistemde i5 Barası İçin Güç Dengesi

IEEE-33 Bara 1. Etkinlik

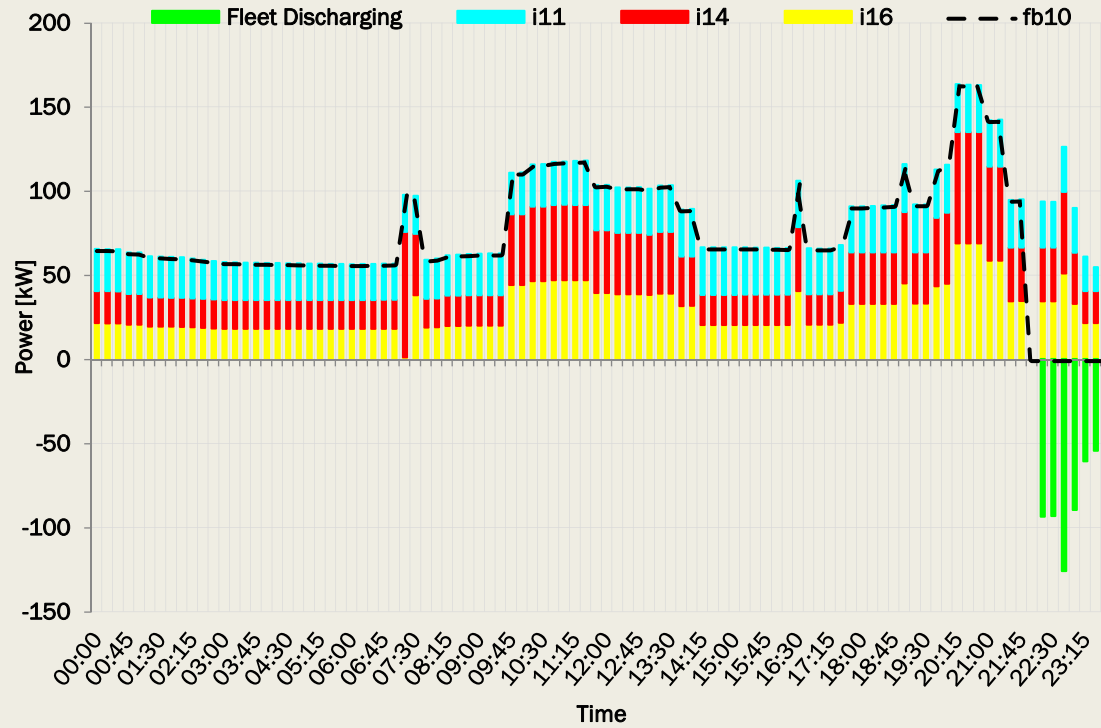


33 Baralı Sistemde i11 Barası İçin Güç Dengesi

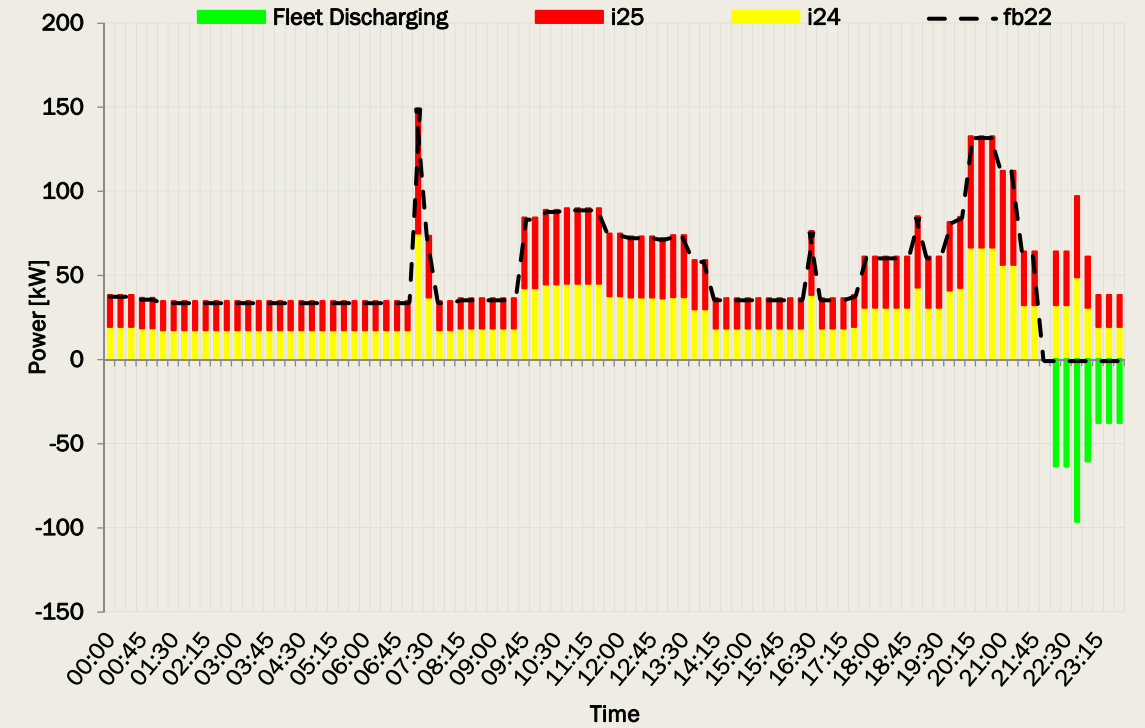


33 Baralı Sistemde i23 Barası İçin Güç Dengesi

IEEE-33 Bara 2. Etkinlik

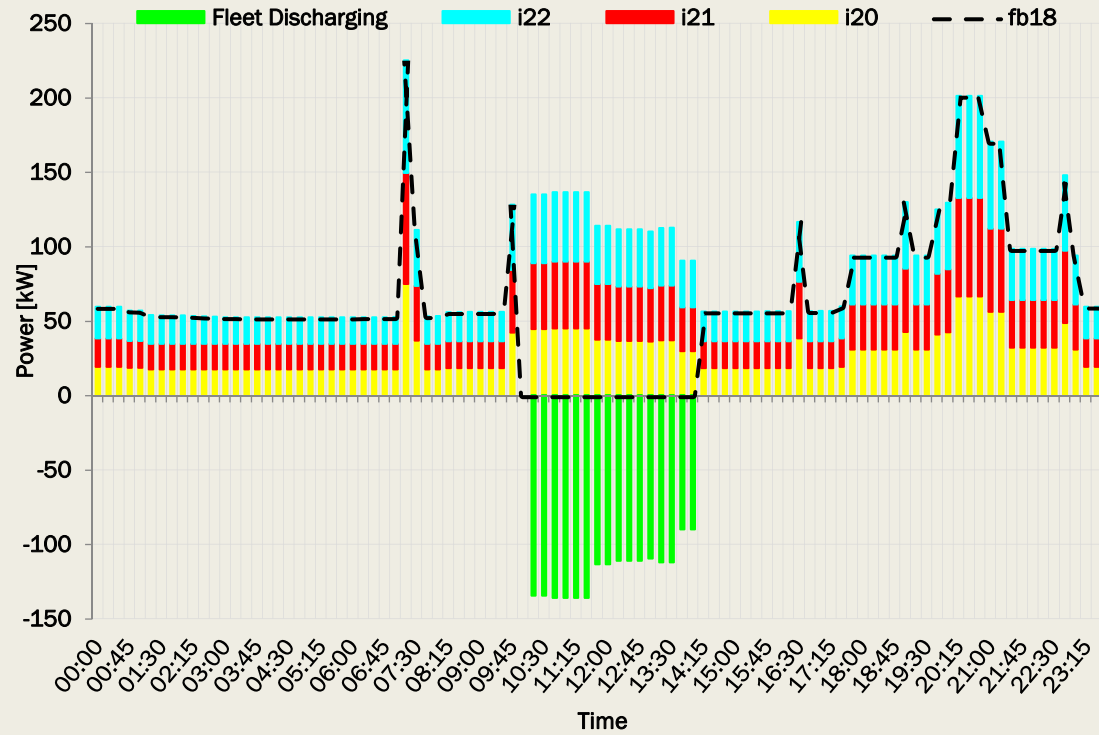


33 Baralı Sistemde i11 Barası İçin Güç Dengesi

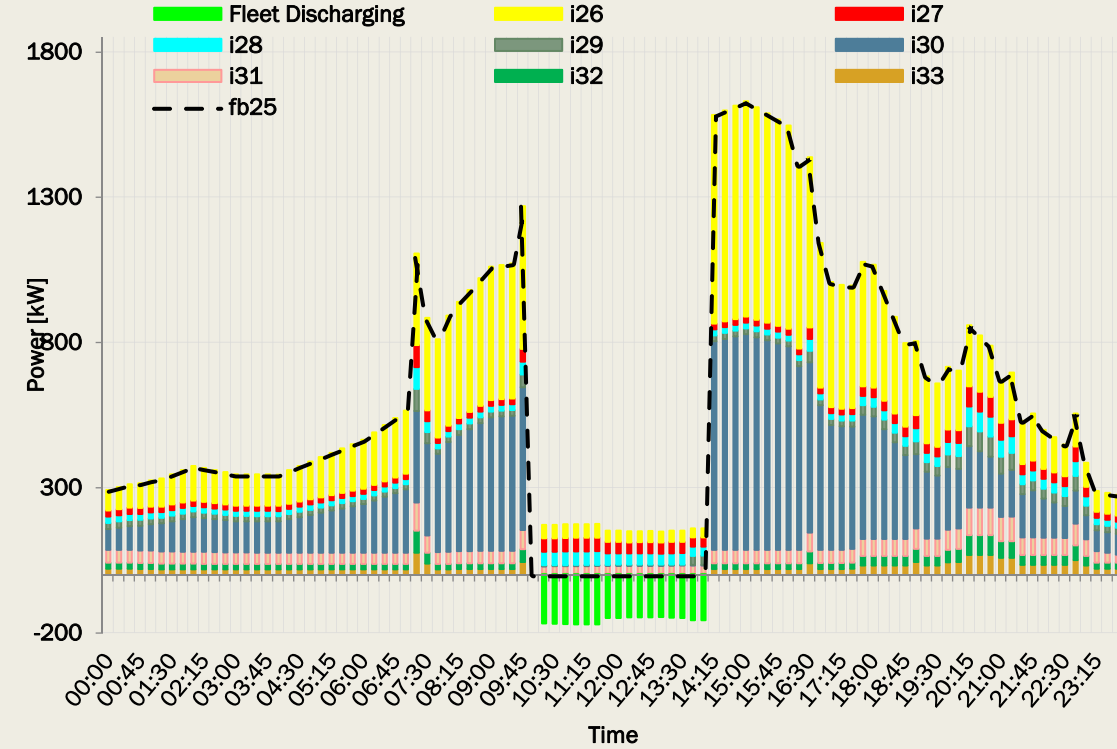


33 Baralı Sistemde i23 Barası İçin Güç Dengesi

IEEE-33 Bara 3. Etkinlik



33 Baralı Sistemde i19 Barası İçin Güç Dengesi



33 Baralı Sistemde i26 Barası İçin Güç Dengesi

Bara Sistemi	Arıza Oluşan Bara	Soket Sayısı	Arıza Oluşan Saat	Arıza Süresi	Toplam Enerji Talebi [kWh]	Evlerden Karşılanan Toplam Enerji [kWh]	%
5 Bara	i3	15	10:15	2	4377,79	2948,95	67,36161397
5 Bara	i3	50	10:15	2	4377,79	4100,29	93,66118521
33 Bara	i11 , i23	25 , 25	10:00	4	6270,14	5880,37	93,78371137
33 Bara	i11 , i23	25 , 25	22:00	2h15m	2568,28	1933,22	75,27294532
33 Bara	i19 , i26	10 , 25	10:00	4	11654,66	8863,65	76,05241165